

IV. DETAILED FINITE ELEMENT ANALYSIS

Detailed finite element analyses were performed before the experimental modal analyses to aid in the selection of instrumentation locations and to give indications of the frequencies associated with the lower modes of the structure. All calculations were performed with the ABAQUS finite element code (ABAQUS User Manual (1994)) on a CRAY Y-MP computer. Mesh generation and post-processing were done with PATRAN (P3/PATRAN User Manual (1992)) on a Silicon Graphics workstation. In addition to providing information that would aid in the selection of instrumentation options, these models can be used in conjunction with experimental modal data to obtain an indirect indication of the composite action exhibited by the bridge. Another use of these models was to ascertain the degree of nonlinearity that the structure exhibited after each stage of damage. Finally, these detailed finite element analyses were subsequently compared to results obtained with simple beam models of the bridge to assess the accuracy of the beam models.

IV. A. Preliminary Calculations

Before analyzing the bridge structure, the ABAQUS finite element code was exercised on a beam problem to verify that, for a well-defined problem, the dynamic properties predicted by ABAQUS agreed with closed-form solutions. A W40x328 beam 600-in. long was modeled five ways :

1. Using the 3-node general beam section elements, where the analyst must enter all relevant cross-section properties. These properties were obtained from an American Institute of Steel Construction Manual (AISC (1989)).
2. Using the 3-node I-section beam elements, where the cross-section dimensions are specified and ABAQUS calculates the cross-sectional properties.
3. Using 8-node shell elements to model the web and flange. The mesh for this model is shown in Fig. 33 along with the first bending (strong and weak axis) modes and the first torsional mode.
4. Using 8-node shell elements to model the web and beam elements to model the flange. Nodes for the beam elements are located at the centroid of the flange and constrained to the corresponding nodes representing the top and bottom edge of the web.
5. Using 8-node shell elements to model the web and beam elements to model the flange. Nodes that form the top and bottom edge of the web are used to define the flange as well, and the centroid option is used to define the location of the centroid of the flange.

In all cases, the beam was modeled with ten elements along its length. Generic steel material properties of $E_{\text{steel}} = 29,000,000$ psi, $\nu_{\text{steel}} = 0.3$, $\mu_{\text{steel}} = 0.284$ lbm/in³, were specified in these analyses. Free boundary conditions were specified at each end of the beam.

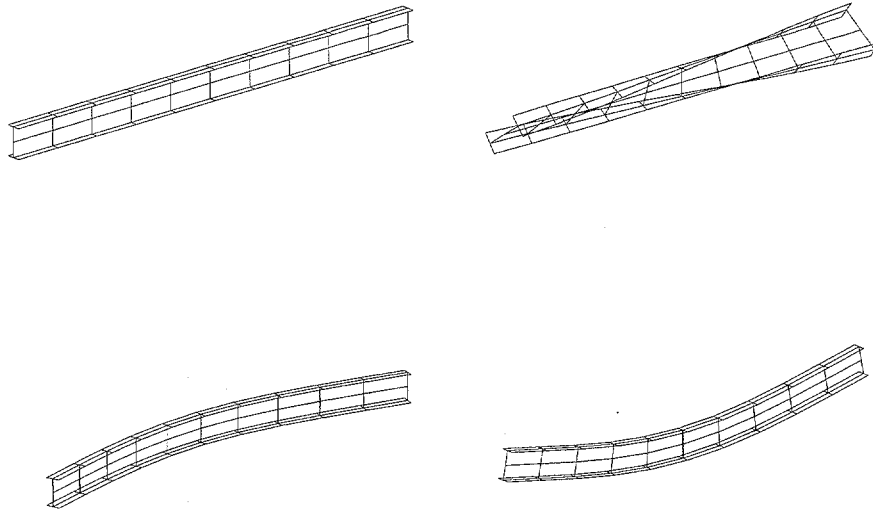


Fig. 33. Shell element model of the W40X328 beam, first bending modes, and first torsional mode.

Results from modal analyses were compared with closed-form solutions given by Blevins (1979) to verify that ABAQUS was accurately calculating the dynamic properties of this beam. The closed-form solution for the resonant frequencies associated with free boundary conditions are

$$f_b = \frac{(\lambda_i)^2}{2\pi L^2} \sqrt{\frac{EI}{\mu A}}, \text{ and} \quad (2)$$

$$f_t = \frac{1}{2L} \sqrt{\frac{JG}{\mu I_p}}, \quad (3)$$

where f_b = the bending mode frequency in Hz,

$(\lambda_i)^2 = 22.4$ for Mode 1 (a factor to account for boundary conditions, see Blevins (1979)),

L = the length of the beam,

E = the modulus of elasticity,

I = the cross-sectional area moment of inertia,

A = cross-sectional area,

f_t = the torsional mode frequency in Hz,

J = the torsional constant for the cross section,

G = the shear modulus,

μ = the mass density, and

I_p = Polar moment of inertia about the center of mass.

It should be noted that the expression for the torsional frequency is only exact for circular cross-sections.

Table VII summarizes the results obtained. From these results it is evident that all methods of discretizing the beam give comparable results for the calculated dynamic properties of the beam.

| TABLE VII | | | | | | |
|---|--------------------------------|----------|---------|---------|---------|---------|
| Comparison of Beam Dynamic Properties Calculated by ABAQUS with Closed-Form Solutions: Free Boundary Conditions | | | | | | |
| | Resonant Frequency (Hz) | | | | | |
| MODE | closed form | model 1* | model 2 | model 3 | model 4 | model 5 |
| 1st Torsion | 5.08 | 5.07 | 5.31 | 5.03 | 5.40 | 5.43 |
| 1st weak axis bending | 8.10 | 8.09 | 8.37 | 8.06 | 8.12 | 8.12 |
| 1st strong axis bending | 32.5 | 31.6 | 32.1 | 30.2 | 29.9 | 30.0 |

* Model refers to the elements and options used to discretize the beam as discussed in Sec. IV A.

IV. B. Undamaged Structure

As shown in Fig. 34, the cross section of the I-40 Bridge shown in Fig. 3 has been idealized as consisting of the following components:

1. A concrete slab of constant thickness with a cross-sectional area equivalent to that of the actual slab shown in Fig. 3.
2. Two steel plate girders.
3. Three steel stringers.
4. Steel floor beams (not shown in Fig. 34)

After the beam study was complete, detailed, finite element models of the bridge were developed. The first model uses 8-node shell elements to model the web of the plate girder and the concrete deck shown in Fig. 34. Three-node beam elements were used to model the stringers, floor beam, and flanges of the plate girder. Twenty-node continuum elements were used to model the concrete piers. Horizontal and vertical stiffeners on the plate girder, the diagonal bracing, and the concrete rebar were not incorporated in this model. Generic material properties were used. The steel material properties used in the preliminary beam study (see Sec. IV. A) were also used in this model. The concrete properties used were