

# ***In-situ* real-time monitoring of biomolecular interactions based on resonating microcantilevers immersed in a viscous fluid**

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We report the precise (noise-free) *in-situ* real-time monitoring of a specific protein antigen-antibody interaction by using a resonating microcantilever immersed in a viscous fluid. In this work, we utilized a resonating piezoelectric thick film microcantilever, which exhibits the high quality factor (e.g.  $Q = 15$ ) in a viscous liquid at a viscosity comparable to that of human blood serum. This implies a great potential of our resonating microcantilever to *in-situ* biosensor applications. It is shown that our microcantilever enables us to monitor the C reactive protein (CRP) antigen-antibody interactions in real-time, providing an insight into the protein binding kinetics.

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Nanomechanical microcantilevers have played a vital role in understanding the various physical phenomena such as temperature,<sup>1</sup> mass sensing,<sup>2</sup> molecular interactions,<sup>3</sup> protein conformations,<sup>4</sup> and protein/polymer conformation transitions.<sup>5</sup> In a recent decade, a resonating microcantilever has allowed the highly sensitive detection of various molecules. The ultrahigh sensitivity of a resonating cantilever is attributed to scaling down that increases the dynamical response ranges as well as the sensitivity. For instance, a recent study by Yang, et al.<sup>6</sup> provided that a resonating micron-scale cantilever enabled the molecular mass sensing in the order of zeptogram. Moreover, a resonating microcantilever has allowed the highly sensitive label-free detection of biomolecules.<sup>7-10</sup>

For a sensitive, reliable real-time monitoring of biomolecular interactions, it is desirable for a resonating microcantilever to perform vibration modes with a high quality factor and a high-frequency dynamical range in a viscous liquid environment. However, most of resonating microcantilevers possess the low quality factor in a liquid environment (e.g.  $Q = \sim 5$  in a liquid environment for Ref. 11), in spite of their high quality factor in normal air.<sup>8,11</sup> Consequently, the dynamical response change (resonant frequency shift) to biomolecular interactions was typically measured in normal air before and after bioassay.<sup>10,12</sup> It is, thus, demanded to develop a resonating microcantilever that are able to overcome the viscous liquid damping effects such that it exhibits the high quality factor in a liquid environment. Recently, we developed the piezoelectric thick film microcantilever that bears a high quality factor in a liquid environment (e.g.  $Q = \sim 25$  in water environment).<sup>13</sup> In this work, we report that our piezoelectric thick film microcantilever exhibits the high quality factor (e.g.  $Q = 15 \sim 25$ ) in a viscous liquid, even at a viscosity comparable to that of blood serum (i.e.  $\sim 4.5$

cPs). This suggests that our microcantilever may be applicable to an *in-situ* biosensor. Remarkably, in this work, it is shown that our microcantilever enables the precise (noise-free) *in-situ* real-time monitoring of protein-protein interactions.

For an *in-situ* real-time monitoring of biomolecular interactions, we utilized a piezoelectric thick film microcantilever, which are capable of self-actuating/sensing by using piezoelectric and converse piezoelectric effects. The piezoelectric thick film microcantilever, whose dimension is  $500 \times 35 \times 580 \mu\text{m}^3$  or  $500 \times 35 \times 500 \mu\text{m}^3$  (width  $\times$  thickness  $\times$  length), fabricated by MEMS process coupled with screen-printing method (See Fig. 1).<sup>13</sup> In order to be operated in a viscous liquid environment, a piezoelectric thick film microcantilever was coated with 1  $\mu\text{m}$  thick parylene-C, which serves as an electrically insulating biocompatible barrier against moisture and bio-fluids. For biomolecular recognitions, the surface of our microcantilever was functionalized by Calixcrown self-assembled monolayer (SAM) that can bind the amine group of protein antibodies, consequently enabling one to immobilize protein antibodies on a cantilever surface.<sup>8</sup> After antibody immobilization process, bovine serum albumin (BSA) was used as a blocking agent to inhibit the non-specific binding.<sup>8,10</sup> The biologically functionalized microcantilever was, then, mounted in a liquid cell that has 300  $\mu\text{m}$  wide micro-channels and 16.5  $\mu\text{l}$  volume reaction chamber. For measuring a resonant frequency of a microcantilever immersed in a viscous liquid environment, an electrically insulating liquid (Fluorinert<sup>TM</sup>, 3M), whose viscosity is in a range of 1.4 cPs to 4.7 cPs, was injected into the inlet of a liquid cell until the channel of a liquid cell was filled with fluid. For an *in-situ* real-time monitoring of biomolecular interactions, C reactive protein (CRP) antigen dissolved phosphate buffered saline (PBS) solution (pH 7.4) was injected into a liquid cell, in which a biologically functionalized

microcantilever was mounted. In addition, in order to confirm the specific binding on a cantilever surface, the negative control experiment was conducted by injecting BSA dissolved PBS solution into a liquid cell. The resonance behavior of our microcantilever in a liquid cell was measured by using a laser doppler interferometric vibrometer (NEO ARK Co., Japan).

The resonance behavior of a piezoelectric thick film microcantilever is very consistent with classical elasticity theory. In our previous work,<sup>13</sup> it was reported that the resonant frequency of our microcantilever in normal air is well described by simple harmonic oscillator model. As shown in Fig. 2, our resonating microcantilever with a length of 580  $\mu\text{m}$  in normal air possesses the resonant frequency of 47 kHz with a high quality factor  $Q \approx 65$ . Remarkably, our microcantilever exhibits the high quality factor even in a viscous liquid environment. Specifically, for our microcantilever the quality factor  $Q$  in an electrically insulating liquid, whose viscosity in a range of 1.4 cPs to 4.7 cPs, ranges from 15 (for 4.7 cPs) to 25 (for 1.4 cPs) (See Fig. 2). This  $Q$  value is much higher than any  $Q$  values of any other microcantilevers reported in literatures<sup>11</sup>. This may shed light on that our microcantilever enables the precise (noise-free) *in-situ* real-time monitoring of biomolecular interactions. The resonance behavior of our microcantilever in a liquid environment is also well depicted by elasticity theory. The elasticity theory<sup>9</sup> provides the resonant frequency  $\omega_i$  of a cantilever immersed in a viscous fluid such as

$$\omega_i = \sqrt{\theta\omega_{0,i}^2 - \eta^2} \quad (1)$$

Here,  $\theta$  is a dimensionless parameter defined as  $\theta = m_c/(m_c + m_l)$ , where  $m_c$  is a cantilever's mass and  $m_l$  is the hydrodynamic loading arising from surrounding fluid acting on a cantilever.<sup>14</sup>  $\omega_{0,i}$  is a resonant frequency of a cantilever in normal air.  $\eta$  is a

dimensionless damping coefficient given by  $\eta = \gamma L / 2(m_c + m_l)$ , where  $L$  is a cantilever length and  $\gamma$  is a viscosity (i.e.  $\gamma = 1.4$  cPs  $\sim 4.7$  cPs). It should be noted that the hydrodynamic loading  $m_l$  is given by<sup>14</sup>

$$\frac{m_l}{m_c} = \left( \frac{w}{t_c} \right) \left( 1 + \frac{4}{(\lambda_i w / L) \sqrt{w^2 \omega_{0,i}^2 / \nu}} \right) \left( \frac{\rho_l}{\rho_c} \right) \quad (2)$$

where  $t_c$  is a thickness of a cantilever,  $w$  is a width of a cantilever,  $\nu$  is a kinetic viscosity ( $\nu = 10^{-6}$  m<sup>2</sup>/s),  $\lambda_i$  is a constant satisfying the transcendental equation (i.e.  $\lambda_i = 1.87$ ),  $\rho_l$  is a density of a liquid ( $\rho_l = 1000$  kg/m<sup>3</sup>), and  $\rho_c$  is a density of a cantilever ( $\rho_c = 4543$  kg/m<sup>3</sup>). With the cantilever's mass  $m_c$  given by  $m_c = \rho_c V$  (i.e.  $m_c = \sim 4 \times 10^{-8}$  kg), where  $V$  is a cantilever's volume, the hydrodynamic loading,  $m_l$ , is estimated as  $m_l = \sim 1.2 \times 10^{-7}$  kg (See Eq. 2). With given parameters for Eq. 1, it can be easily shown that a hydrodynamic loading effect rather than a damping effect plays a role in dynamical response of our microcantilever immersed in a liquid (i.e.  $\theta \omega_{0,i}^2 / \eta^2 \gg 1$ ).<sup>15</sup> Hence, the resonant frequency of our microcantilever immersed in a viscous liquid is given by  $\omega_i = \omega_{0,i} \sqrt{\theta}$ . This suggests that our microcantilever operated in an electrically insulating liquid is expected to exhibit the resonant frequency of  $\sim 23$  kHz, consistent with our experimental data (See Fig. 2).

As stated above, a high quality factor in a viscous liquid environment (e.g.  $Q = \sim 15$  at viscosity of  $\sim 4.7$  cPs) implies a great potential to an *in-situ* real-time monitoring of biomolecular interactions (i.e. CRP antigen-antibody interactions) by measuring the resonance frequency shift induced by biomolecular recognitions. The resonant frequency shift, for a microcantilever with a length of 500  $\mu$ m, was recorded every 1 min after injecting CRP antigen dissolved solution. It should be noted that the cantilever

with a length of 500  $\mu\text{m}$  exhibits the resonance of 62.18 kHz in normal air and the resonance of 36.11 kHz in a PBS solution, consistent with elasticity theory. The specific interactions between our microcantilever and CRP antigens were proven by negative control experiment, showing no resonant frequency shift, so that non-specific interactions are unlikely to occur in our microcantilever surface (See Fig. 4).

We consider the curvature effect of protein monolayer on the resonance of a cantilever. The resonant frequency,  $\chi_i$ , of a cantilever after attachment of protein monolayer is given by  $\chi_i = \omega_i \sqrt{1 + \alpha}$ . Here  $\omega_i$  is a resonant frequency of a bare cantilever, and a parameter  $\alpha$  is given by  $\alpha = \zeta_p / \zeta_c$ , where  $\zeta_p$  and  $\zeta_c$  are bending rigidities of protein monolayer and a bare cantilever, respectively. Classical elasticity theory provides the bending rigidity of a bare cantilever as  $\zeta_c = 1.27 \times 10^{-7} \text{ Nm}^2$ , whereas the bending rigidity of protein monolayer is estimated as  $\zeta_p \approx E_p w t_p (t_c/2)^2 = 8.4 \times 10^{-13} \text{ Nm}^2$  with given Young's modulus  $E_p = \sim 1 \text{ GPa}$ <sup>16</sup> and thickness  $t_p = \sim 10 \text{ nm}$ <sup>17</sup>. This indicates that curvature effect of protein monolayer does not play any role on the resonance of a cantilever. Moreover, the surface stress induced by intermolecular interactions between adsorbed proteins may be insignificant for the resonance of a cantilever, because the surface stress effect (intermolecular interactions) may dominate the dynamical behavior of a cantilever when a cantilever's thickness becomes comparable to that of protein layer.<sup>18</sup>

For clarifying the origin of resonant frequency shift due to protein antigen-antibody interactions, we take into account the resonant frequency shift, which was measured in normal air before and after bioassay, due to CRP antigen-antibody interactions (See Fig. 3). Since the curvature effect and/or surface stress effect of protein monolayer are not related to resonance behavior of a cantilever, the resonant frequency

shift in normal air,  $\Delta\omega_0$ , may be ascribed to the mass of adsorbed proteins.<sup>9</sup>

$$\frac{\Delta\omega_0}{\omega_0} \approx -\frac{1}{2} \frac{\Delta m}{m_c} \quad (3)$$

where  $\omega_0$  is the resonant frequency of a cantilever operated in normal air before bioassay, and  $\Delta m$  is the mass of adsorbed molecules. With  $\Delta\omega_0 = 2.79$  kHz and  $\omega_0 = 62.18$  kHz, the mass of adsorbed proteins is estimated as  $\Delta m = 3.5$  ng. Fig. 4 shows the resonant frequency shift that was measured in the liquid environment during protein antigen-antibody interactions. It is remarkable that, for protein antigen-antibody interactions, the resonant frequency shift measured in liquid environment is larger than that estimated in normal air. It is consistent with previous works<sup>19</sup> which reported that, for protein antigen-antibody interactions, the resonant frequency shift for a mass sensor (e.g. quartz crystal microbalance) was estimated in liquid environment larger than that measured in normal air by factor of  $\sim 4$ . This phenomenon is attributed to protein antigen-antibody interactions increasing the hydrophilicity that changes hydrodynamic loading coupled to resonance behavior of a mass sensor.<sup>19</sup> Accordingly, the resonant frequency shift induced by protein antigen-antibody interactions for a cantilever immersed in a liquid is originated from the change of hydrodynamic loading due to increase of hydrophilicity during antigen-antibody interactions.

$$\frac{\Delta\omega}{\omega} = \frac{1}{2} \frac{\Delta m_l}{m_l} (1 - \theta) + \frac{1}{2} \frac{\Delta m}{m_c} \theta \quad (4)$$

Here,  $\Delta\omega$  and  $\omega$  are the resonant frequency shift and the reference resonant frequency (before bioassay) which are measured in liquid, respectively,  $\Delta m_l$  is the change of hydrodynamic loading induced by antigen-antibody interactions, and  $\Delta m$  is the mass of adsorbed proteins. It provides that the change of hydrodynamic loading  $\Delta m_l$  due to CRP antigen-antibody interactions is estimated as  $\Delta m_l = 9.3 \times 10^{-8}$  g. Moreover, as shown in

Fig. 4, the resonant frequency shift follows the Langmuir kinetic model, indicating that our microcantilever may allow for gaining insight into kinetics of protein-protein interactions. Further, high quality factor of our microcantilever operated in liquid enables the noise-free real-time monitoring of protein-protein interactions, since  $1/Q$  represents the intrinsic noise of a system.<sup>20</sup>

In summary, we report the *in-situ* real-time monitoring of CRP antigen-antibody interactions by using a piezoelectric thick film microcantilever that possesses the high quality factor even in a viscous liquid environment. It was shown that resonance of an *in-situ* cantilever is well depicted by hydrodynamic loading, and that the protein antigen-antibody interactions increase the hydrophilicity resulting in a change of hydrodynamic loading coupled to resonance behavior of a cantilever. Moreover, the precise *in-situ* real-time monitoring of protein-protein interactions is ascribed to high quality factor of our microcantilever. Consequently, our microcantilever enables us to precisely gain insight into kinetics of protein-protein interactions. In the long run, our piezoelectric thick film microcantilevers may allow the precise real-time monitoring of various biomolecular interactions such as DNA-DNA interactions, DNA-protein interactions, and protein-small-molecule interactions.

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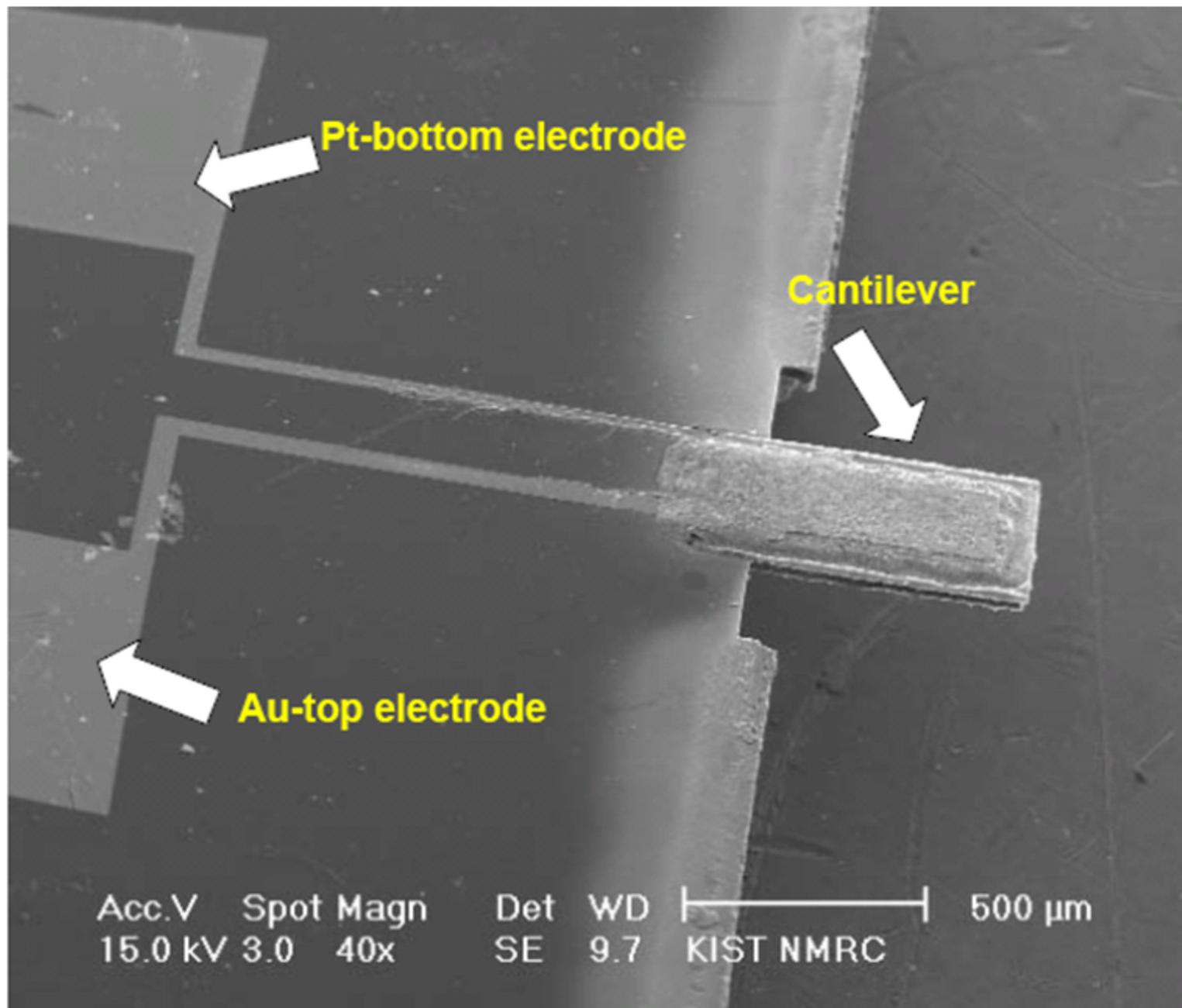
## Figure Captions

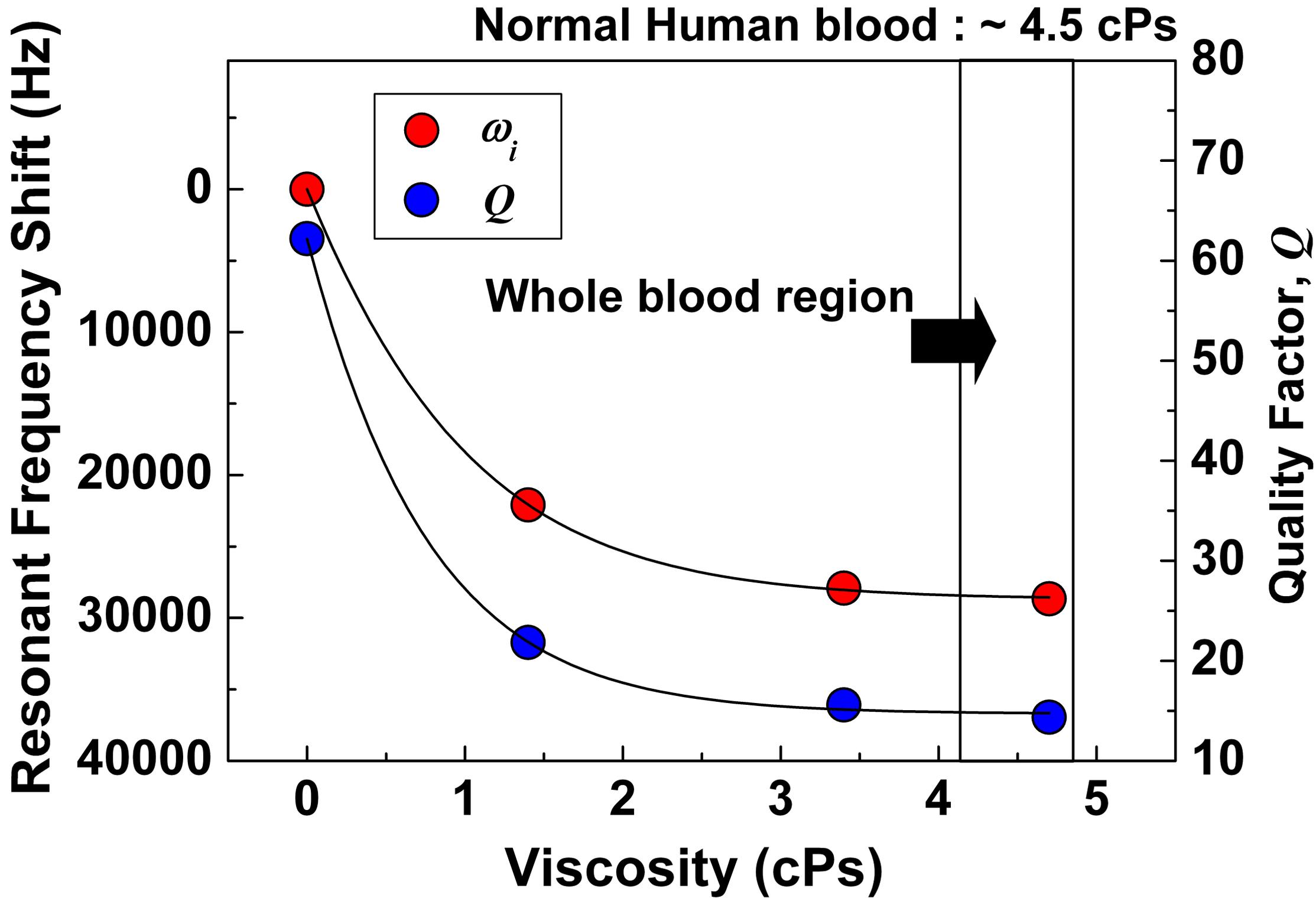
Fig. 1. Scanning electron microscopy (SEM) image of a piezoelectric thick film microcantilever, whose dimension is  $500 \times 35 \times 580 \mu\text{m}^3$  (width  $\times$  thickness  $\times$  length).

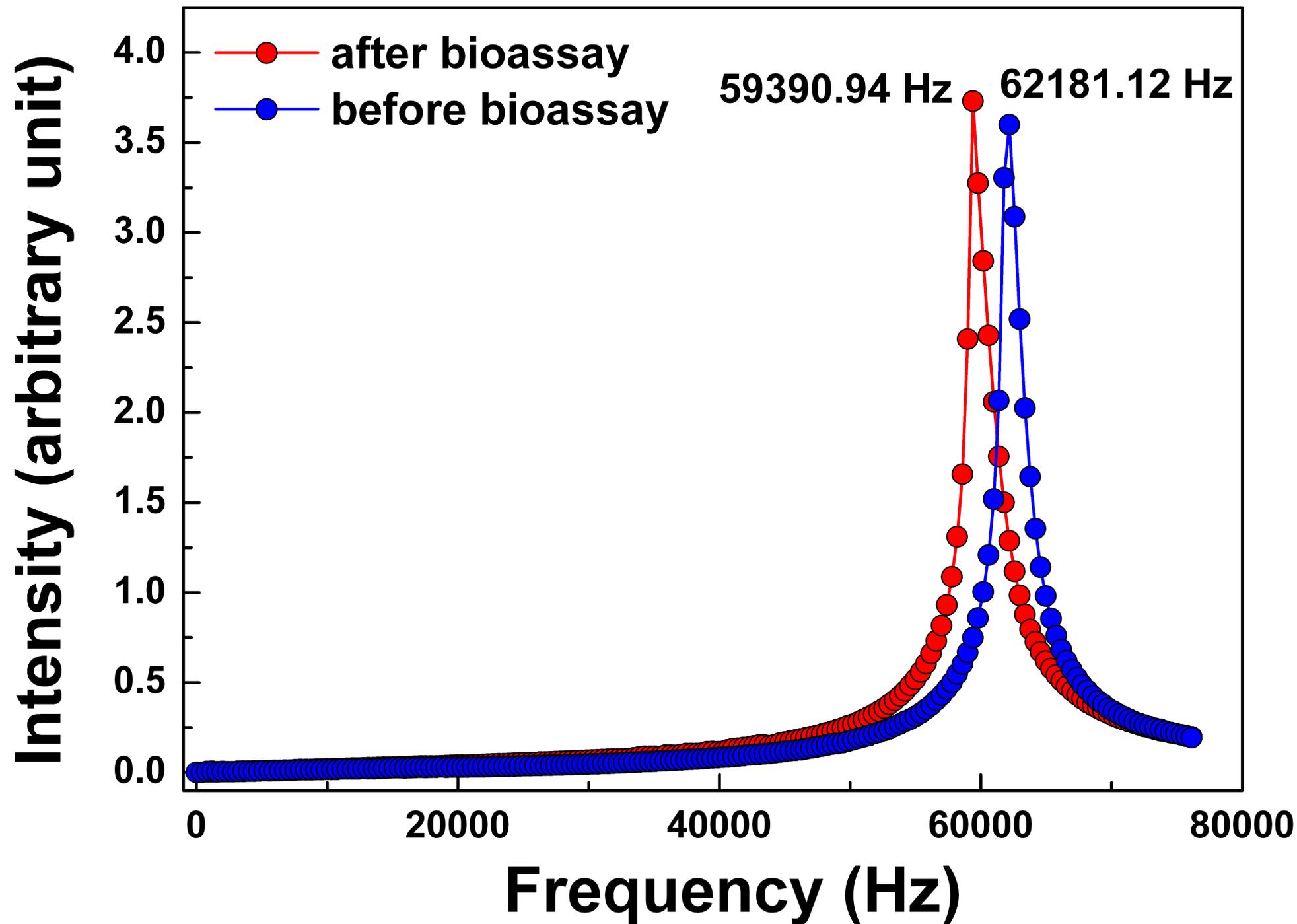
Fig. 2. Resonant frequency shift due to virtual mass and quality factor for our microcantilever in a viscous liquid.

Fig. 3. Resonance behavior of PZT thick film microcantilever, operated in normal air, before and after bioassay

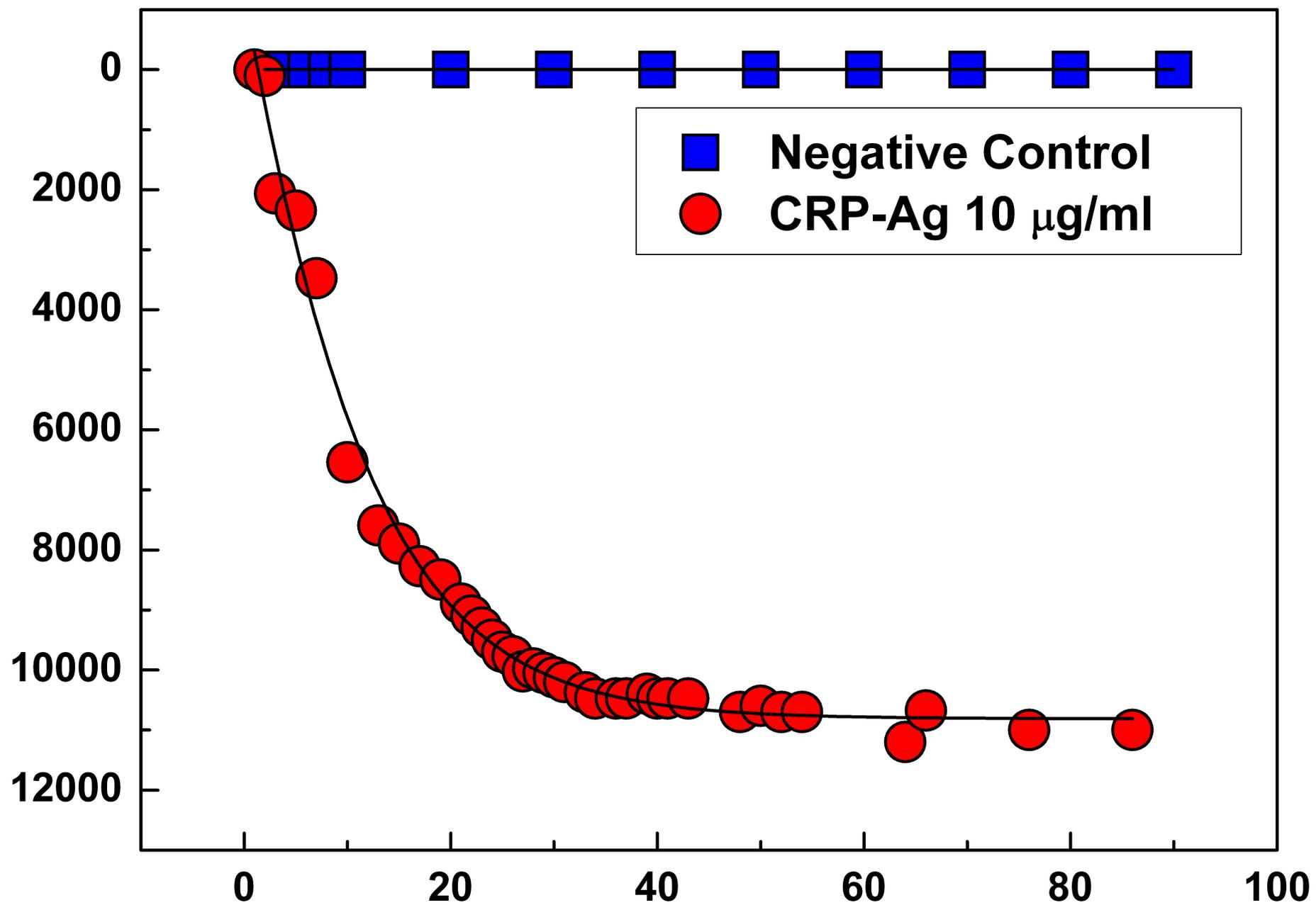
Fig. 4. *In-situ* real-time monitoring of resonant frequency shift induced by CRP antigen-antibody interactions







**Resonant Frequency Shift (Hz)**



**CRP Ag-Ab interaction time (min)**