

***In-situ* real-time monitoring of biomolecular interactions based on resonating microcantilevers immersed in a viscous fluid**

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We report the precise (noise-free) *in-situ* real-time monitoring of a specific protein antigen-antibody interaction by using a resonating microcantilever immersed in a viscous fluid. In this work, we utilized a resonating piezoelectric thick film microcantilever, which exhibits the high quality factor (e.g. $Q = 15$) in a viscous liquid at a viscosity comparable to that of human blood serum. This implies a great potential of our resonating microcantilever to *in-situ* biosensor applications. It is shown that our microcantilever enables us to monitor the C reactive protein (CRP) antigen-antibody interactions in real-time, providing an insight into the protein binding kinetics.

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Nanomechanical microcantilevers have played a vital role in understanding the various physical phenomena such as temperature,¹ mass sensing,² molecular interactions,³ protein conformations,⁴ and protein/polymer conformation transitions.⁵ In a recent decade, a resonating microcantilever has allowed the highly sensitive detection of various molecules. The ultrahigh sensitivity of a resonating cantilever is attributed to scaling down that increases the dynamical response ranges as well as the sensitivity. For instance, a recent study by Yang, et al.⁶ provided that a resonating micron-scale cantilever enabled the molecular mass sensing in the order of zeptogram. Moreover, a resonating microcantilever has allowed the highly sensitive label-free detection of biomolecules.⁷⁻¹⁰

For a sensitive, reliable real-time monitoring of biomolecular interactions, it is desirable for a resonating microcantilever to perform vibration modes with a high quality factor and a high-frequency dynamical range in a viscous liquid environment. However, most of resonating microcantilevers possess the low quality factor in a liquid environment (e.g. $Q = \sim 5$ in a liquid environment for Ref. 11), in spite of their high quality factor in normal air.^{8,11} Consequently, the dynamical response change (resonant frequency shift) to biomolecular interactions was typically measured in normal air before and after bioassay.^{10,12} It is, thus, demanded to develop a resonating microcantilever that are able to overcome the viscous liquid damping effects such that it exhibits the high quality factor in a liquid environment. Recently, we developed the piezoelectric thick film microcantilever that bears a high quality factor in a liquid environment (e.g. $Q = \sim 25$ in water environment).¹³ In this work, we report that our piezoelectric thick film microcantilever exhibits the high quality factor (e.g. $Q = 15 \sim 25$) in a viscous liquid, even at a viscosity comparable to that of blood serum (i.e. ~ 4.5

cPs). This suggests that our microcantilever may be applicable to an *in-situ* biosensor. Remarkably, in this work, it is shown that our microcantilever enables the precise (noise-free) *in-situ* real-time monitoring of protein-protein interactions.

For an *in-situ* real-time monitoring of biomolecular interactions, we utilized a piezoelectric thick film microcantilever, which are capable of self-actuating/sensing by using piezoelectric and converse piezoelectric effects. The piezoelectric thick film microcantilever, whose dimension is $500 \times 35 \times 580 \mu\text{m}^3$ or $500 \times 35 \times 500 \mu\text{m}^3$ (width \times thickness \times length), fabricated by MEMS process coupled with screen-printing method (See Fig. 1).¹³ In order to be operated in a viscous liquid environment, a piezoelectric thick film microcantilever was coated with 1 μm thick parylene-C, which serves as an electrically insulating biocompatible barrier against moisture and bio-fluids. For biomolecular recognitions, the surface of our microcantilever was functionalized by Calixcrown self-assembled monolayer (SAM) that can bind the amine group of protein antibodies, consequently enabling one to immobilize protein antibodies on a cantilever surface.⁸ After antibody immobilization process, bovine serum albumin (BSA) was used as a blocking agent to inhibit the non-specific binding.^{8,10} The biologically functionalized microcantilever was, then, mounted in a liquid cell that has 300 μm wide micro-channels and 16.5 μl volume reaction chamber. For measuring a resonant frequency of a microcantilever immersed in a viscous liquid environment, an electrically insulating liquid (FluorinertTM, 3M), whose viscosity is in a range of 1.4 cPs to 4.7 cPs, was injected into the inlet of a liquid cell until the channel of a liquid cell was filled with fluid. For an *in-situ* real-time monitoring of biomolecular interactions, C reactive protein (CRP) antigen dissolved phosphate buffered saline (PBS) solution (pH 7.4) was injected into a liquid cell, in which a biologically functionalized

microcantilever was mounted. In addition, in order to confirm the specific binding on a cantilever surface, the negative control experiment was conducted by injecting BSA dissolved PBS solution into a liquid cell. The resonance behavior of our microcantilever in a liquid cell was measured by using a laser doppler interferometric vibrometer (NEO ARK Co., Japan).

The resonance behavior of a piezoelectric thick film microcantilever is very consistent with classical elasticity theory. In our previous work,¹³ it was reported that the resonant frequency of our microcantilever in normal air is well described by simple harmonic oscillator model. As shown in Fig. 2, our resonating microcantilever with a length of 580 μm in normal air possesses the resonant frequency of 47 kHz with a high quality factor $Q = \sim 65$. Remarkably, our microcantilever exhibits the high quality factor even in a viscous liquid environment. Specifically, for our microcantilever the quality factor Q in an electrically insulating liquid, whose viscosity in a range of 1.4 cPs to 4.7 cPs, ranges from 15 (for 4.7 cPs) to 25 (for 1.4 cPs) (See Fig. 2). This Q value is much higher than any Q values of any other microcantilevers reported in literatures¹¹. This may shed light on that our microcantilever enables the precise (noise-free) *in-situ* real-time monitoring of biomolecular interactions. The resonance behavior of our microcantilever in a liquid environment is also well depicted by elasticity theory. The elasticity theory⁹ provides the resonant frequency ω_i of a cantilever immersed in a viscous fluid such as

$$\omega_i = \sqrt{\theta \omega_{0,i}^2 - \eta^2} \quad (1)$$

Here, θ is a dimensionless parameter defined as $\theta = m_c/(m_c + m_l)$, where m_c is a cantilever's mass and m_l is the hydrodynamic loading arising from surrounding fluid acting on a cantilever.¹⁴ $\omega_{0,i}$ is a resonant frequency of a cantilever in normal air. η is a

dimensionless damping coefficient given by $\eta = \gamma L / 2(m_c + m_l)$, where L is a cantilever length and γ is a viscosity (i.e. $\gamma = 1.4 \text{ cPs} \sim 4.7 \text{ cPs}$). It should be noted that the hydrodynamic loading m_l is given by¹⁴

$$\frac{m_l}{m_c} = \left(\frac{w}{t_c} \right) \left(1 + \frac{4}{(\lambda_i w / L) \sqrt{w^2 \omega_{0,i}^2 / \nu}} \right) \left(\frac{\rho_l}{\rho_c} \right) \quad (2)$$

where t_c is a thickness of a cantilever, w is a width of a cantilever, ν is a kinetic viscosity ($\nu = 10^{-6} \text{ m}^2/\text{s}$), λ_i is a constant satisfying the transcendental equation (i.e. $\lambda_i = 1.87$), ρ_l is a density of a liquid ($\rho_l = 1000 \text{ kg/m}^3$), and ρ_c is a density of a cantilever ($\rho_c = 4543 \text{ kg/m}^3$). With the cantilever's mass m_c given by $m_c = \rho_c V$ (i.e. $m_c = \sim 4 \times 10^{-8} \text{ kg}$), where V is a cantilever's volume, the hydrodynamic loading, m_l , is estimated as $m_l = \sim 1.2 \times 10^{-7} \text{ kg}$ (See Eq. 2). With given parameters for Eq. 1, it can be easily shown that a hydrodynamic loading effect rather than a damping effect plays a role in dynamical response of our microcantilever immersed in a liquid (i.e. $\theta \omega_{0,i}^2 / \eta^2 \gg 1$).¹⁵ Hence, the resonant frequency of our microcantilever immersed in a viscous liquid is given by $\omega_i = \omega_{0,i} \sqrt{\theta}$. This suggests that our microcantilever operated in an electrically insulating liquid is expected to exhibit the resonant frequency of $\sim 23 \text{ kHz}$, consistent with our experimental data (See Fig. 2).

As stated above, a high quality factor in a viscous liquid environment (e.g. $Q = \sim 15$ at viscosity of $\sim 4.7 \text{ cPs}$) implies a great potential to an *in-situ* real-time monitoring of biomolecular interactions (i.e. CRP antigen-antibody interactions) by measuring the resonance frequency shift induced by biomolecular recognitions. The resonant frequency shift, for a microcantilever with a length of $500 \text{ }\mu\text{m}$, was recorded every 1 min after injecting CRP antigen dissolved solution. It should be noted that the cantilever

with a length of 500 μm exhibits the resonance of 62.18 kHz in normal air and the resonance of 36.11 kHz in a PBS solution, consistent with elasticity theory. The specific interactions between our microcantilever and CRP antigens were proven by negative control experiment, showing no resonant frequency shift, so that non-specific interactions are unlikely to occur in our microcantilever surface (See Fig. 4).

We consider the curvature effect of protein monolayer on the resonance of a cantilever. The resonant frequency, χ_i , of a cantilever after attachment of protein monolayer is given by $\chi_i = \omega_i \sqrt{1 + \alpha}$. Here ω_i is a resonant frequency of a bare cantilever, and a parameter α is given by $\alpha = \zeta_p / \zeta_c$, where ζ_p and ζ_c are bending rigidities of protein monolayer and a bare cantilever, respectively. Classical elasticity theory provides the bending rigidity of a bare cantilever as $\zeta_c = 1.27 \times 10^{-7} \text{ Nm}^2$, whereas the bending rigidity of protein monolayer is estimated as $\zeta_p \approx E_p w t_p (t_c/2)^2 = 8.4 \times 10^{-13} \text{ Nm}^2$ with given Young's modulus $E_p = \sim 1 \text{ GPa}$ ¹⁶ and thickness $t_p = \sim 10 \text{ nm}$ ¹⁷. This indicates that curvature effect of protein monolayer does not play any role on the resonance of a cantilever. Moreover, the surface stress induced by intermolecular interactions between adsorbed proteins may be insignificant for the resonance of a cantilever, because the surface stress effect (intermolecular interactions) may dominate the dynamical behavior of a cantilever when a cantilever's thickness becomes comparable to that of protein layer.¹⁸

For clarifying the origin of resonant frequency shift due to protein antigen-antibody interactions, we take into account the resonant frequency shift, which was measured in normal air before and after bioassay, due to CRP antigen-antibody interactions (See Fig. 3). Since the curvature effect and/or surface stress effect of protein monolayer are not related to resonance behavior of a cantilever, the resonant frequency

shift in normal air, $\Delta\omega_0$, may be ascribed to the mass of adsorbed proteins.⁹

$$\frac{\Delta\omega_0}{\omega_0} \approx -\frac{1}{2} \frac{\Delta m}{m_c} \quad (3)$$

where ω_0 is the resonant frequency of a cantilever operated in normal air before bioassay, and Δm is the mass of adsorbed molecules. With $\Delta\omega_0 = 2.79$ kHz and $\omega_0 = 62.18$ kHz, the mass of adsorbed proteins is estimated as $\Delta m = 3.5$ ng. Fig. 4 shows the resonant frequency shift that was measured in the liquid environment during protein antigen-antibody interactions. It is remarkable that, for protein antigen-antibody interactions, the resonant frequency shift measured in liquid environment is larger than that estimated in normal air. It is consistent with previous works¹⁹ which reported that, for protein antigen-antibody interactions, the resonant frequency shift for a mass sensor (e.g. quartz crystal microbalance) was estimated in liquid environment larger than that measured in normal air by factor of ~ 4 . This phenomenon is attributed to protein antigen-antibody interactions increasing the hydrophilicity that changes hydrodynamic loading coupled to resonance behavior of a mass sensor.¹⁹ Accordingly, the resonant frequency shift induced by protein antigen-antibody interactions for a cantilever immersed in a liquid is originated from the change of hydrodynamic loading due to increase of hydrophilicity during antigen-antibody interactions.

$$\frac{\Delta\omega}{\omega} = \frac{1}{2} \frac{\Delta m_l}{m_l} (1 - \theta) + \frac{1}{2} \frac{\Delta m}{m_c} \theta \quad (4)$$

Here, $\Delta\omega$ and ω are the resonant frequency shift and the reference resonant frequency (before bioassay) which are measured in liquid, respectively, Δm_l is the change of hydrodynamic loading induced by antigen-antibody interactions, and Δm is the mass of adsorbed proteins. It provides that the change of hydrodynamic loading Δm_l due to CRP antigen-antibody interactions is estimated as $\Delta m_l = 9.3 \times 10^{-8}$ g. Moreover, as shown in

Fig. 4, the resonant frequency shift follows the Langmuir kinetic model, indicating that our microcantilever may allow for gaining insight into kinetics of protein-protein interactions. Further, high quality factor of our microcantilever operated in liquid enables the noise-free real-time monitoring of protein-protein interactions, since $1/Q$ represents the intrinsic noise of a system.²⁰

In summary, we report the *in-situ* real-time monitoring of CRP antigen-antibody interactions by using a piezoelectric thick film microcantilever that possesses the high quality factor even in a viscous liquid environment. It was shown that resonance of an *in-situ* cantilever is well depicted by hydrodynamic loading, and that the protein antigen-antibody interactions increase the hydrophilicity resulting in a change of hydrodynamic loading coupled to resonance behavior of a cantilever. Moreover, the precise *in-situ* real-time monitoring of protein-protein interactions is ascribed to high quality factor of our microcantilever. Consequently, our microcantilever enables us to precisely gain insight into kinetics of protein-protein interactions. In the long run, our piezoelectric thick film microcantilevers may allow the precise real-time monitoring of various biomolecular interactions such as DNA-DNA interactions, DNA-protein interactions, and protein-small-molecule interactions.

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Figure Captions

Fig. 1. Scanning electron microscopy (SEM) image of a piezoelectric thick film microcantilever, whose dimension is $500 \times 35 \times 580 \mu\text{m}^3$ (width \times thickness \times length).

Fig. 2. Resonant frequency shift due to virtual mass and quality factor for our microcantilever in a viscous liquid.

Fig. 3. Resonance behavior of PZT thick film microcantilever, operated in normal air, before and after bioassay

Fig. 4. *In-situ* real-time monitoring of resonant frequency shift induced by CRP antigen-antibody interactions







